

Lane modelling algorithm for video-based ADAS

The Industrial Problem

Robert Bosch Kft was interested in a dynamic process for ADAS (Advanced driver assistance systems), which computes the lanes continuously and directly from the data of a stereo-camera and giving a lane model based on only these data.

University of Szeged



Graph theory, discrete geometry, statistics, computer-aided modelling, algorithms, machine learning, programming, psychology.

Robert Bosch Kft.



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Research
group

Company

SZÉCHENYI 2020

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Challenges & Goals

- To identify all possible lanes in the data images
- To implement in embedded framework
- To guarantee small computing capacity
- To optimize the consistency of the lane model

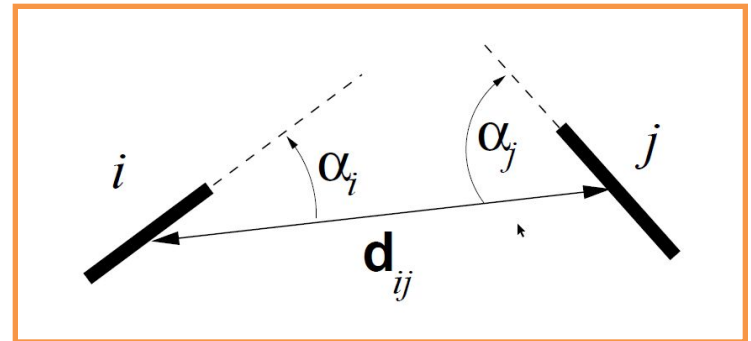


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Mathematical and computational methods and techniques applied

- Probabilistic grouping fields (handling connectivity of line segments)
- Principles of Gestalt psychology
- Graph theory (modelling the similarity)
- Clustering methods: **threshold method** and **spectral clustering**

Parameters for similarity of segments



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Results & Benefits to the company

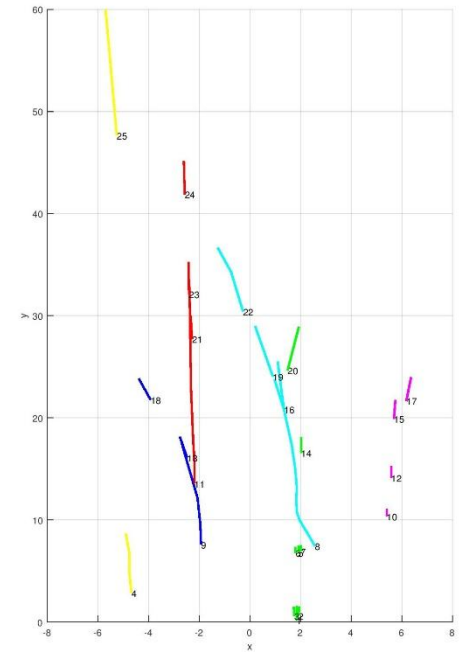
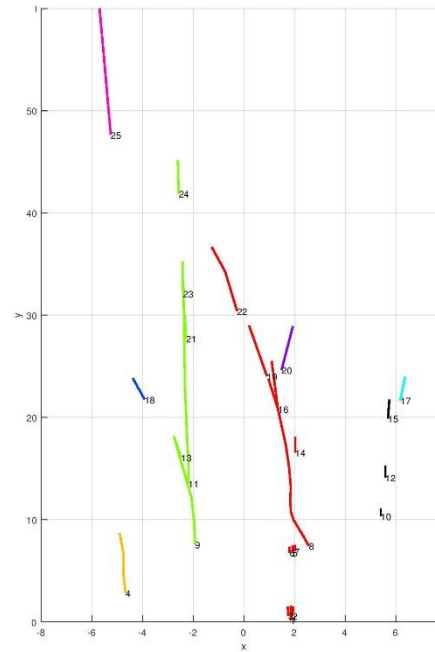
Threshold method:

- Easy to implement
- Efficient runtime
- Number of clusters are computed automatically and dynamically
- Loss of information

Spectral clustering:

- More info is used
- #Clusters is input

These algorithms can be combined.



Result of Algo #1 and Algo #2

The company has efficient clustering algorithms for the lane model problem.